

Definable G homotopy extensions

Tomohiro Kawakami

Department of Mathematics, Faculty of Education, Wakayama University,
Sakaedani Wakayama 640-8510, Japan

kawa@center.wakayama-u.ac.jp

Partially supported by Kakenhi (23540101)

Abstract

Let G be a definably compact definable group, X a definable G set and Y a definable closed G subset of X . We prove that a pair (X, Y) admits a definable G homotopy extension.

2010 *Mathematics Subject Classification*. 14P10, 57S99, 03C64.

Keywords and Phrases. Definable G homotopy extensions, o-minimal, real closed fields.

1 . Introduction.

Let $\mathcal{N} = (R, +, \cdot, <, \dots)$ be an o-minimal expansion of a real closed field R . Everything is considered in \mathcal{N} and every definable map is assumed to be continuous unless otherwise stated.

General references on o-minimal structures are [1], [2], also see [6].

Let G be a definably compact definable group, X a definable G set and Y a definable G subset of X . We say that a pair (X, Y) admits a definable G homotopy extension if for any definable G map f from X to a definable G set Z and any definable G homotopy $F : Y \times [0, 1]_R \rightarrow Z$ with $F(y, 0) = f(y)$ for all $y \in Y$, there exists a definable G homotopy $H : X \times [0, 1]_R \rightarrow Z$ such that $H(x, 0) = f(x)$ for all $x \in X$ and $H|Y \times [0, 1]_R = F$, where $[0, 1]_R = \{x \in R | 0 \leq x \leq 1\}$.

Let $\mathcal{M} = (\mathbb{R}, +, \cdot, <, \dots)$ be an o-minimal expansion of the field \mathbb{R} of real numbers. Definable G sets in \mathcal{M} are studied in [5], [4], [3].

Theorem 1.1 ([4]). *If $\mathcal{N} = \mathcal{M}$, G is a compact definable group, X is a definable G set and Y is a definable closed G subset of X , then (X, Y) admits a definable G homotopy extension.*

In this paper, we generalize Theorem 1.1 to \mathcal{N} .

Theorem 1.2. *Let G be a definably compact definable group. If X is a definable G set and Y is a definable closed G subset of X , then (X, Y) admits a definable G homotopy extension.*

2 . Proof of Theorem 1.2

Let $X \subset R^n$ and $Y \subset R^m$ be definable sets. A continuous map $f : X \rightarrow Y$ is a *definable map* if the graph of f is definable.

A group G is a *definable group* if G is a definable set and the group operations $G \times G \rightarrow G$ and $G \rightarrow G$ are definable.

A definable set X is *definably compact* if for every $a, b \in R \cup \{\infty\} \cup \{-\infty\}$ with $a < b$

and for every definable map $f : (a, b)_R \rightarrow X$, $\lim_{x \rightarrow a+0} f(x)$ and $\lim_{x \rightarrow b-0} f(x)$ exist in X , where $(a, b)_R = \{x \in R \mid a < x < b\}$.

If $R = \mathbb{R}$, then for any definable subset X of \mathbb{R}^n , X is compact if and only if it is definably compact. In general a definably compact definable set is not necessarily compact. For example, if $R = \mathbb{R}_{alg}$, then $[0, 1]_{\mathbb{R}_{alg}} = \{x \in \mathbb{R}_{alg} \mid 0 \leq x \leq 1\}$ is definably compact but not compact.

Let G be a definably compact definable group. A group homomorphism from G to some $O_n(R)$ is an *orthogonal G representation* if it is definable, where $O_n(R)$ means the n th orthogonal group of R . An *orthogonal G representation space* is R^n with the orthogonal action induced from an orthogonal G representation. A *definable G set* means a G invariant definable subset of some orthogonal G representation space.

A G map between definable G sets is a *definable G map* if it is a definable map.

Let X be a definable G set and Y a definable G subset of X . A *definable G retraction from X to Y* is a definable G map $r : X \rightarrow Y$ with $r|_Y = id_Y$. A *definable strong G deformation retraction from X to Y* means a definable G map $F : X \times [0, 1]_R \rightarrow X$ such that $F(x, 0) = x$ for all $x \in X$, $F(y, t) = y$ for all $y \in Y, t \in [0, 1]_R$ and $F(X, 1) = Y$, where the action on $[0, 1]_R$ is trivial. Note that $F(\cdot, 1) : X \rightarrow Y$ is a definable G retraction from X to Y .

By a way similar to the proof of 3.4 [4], we have the following theorem.

Theorem 2.1. *Let G be a definably compact definable group and Y a definable closed G subset of a definable G set X . Then there exists a G invariant definable open neighborhood U of Y in X such that Y is a definable strong G deformation retract of both U and of the closure $\text{cl } U$ of U in X .*

Proposition 2.2. *Let G be a definably compact definable group and A, B disjoint definable closed G subsets of a definable G set X . Then there exists a G invariant definable map $f : X \rightarrow [0, 1]_R$ with $A = f^{-1}(0)$ and $B = f^{-1}(1)$.*

Proof. By 10.2.8 [1], X/G is a definable set and the orbit map $\pi : X \rightarrow X/G$ is a definable map. Since A, B are definable and closed, $\pi(A), \pi(B)$ are definably closed sets. By 6.3.8 [1], there exists a definable map $h : X/G \rightarrow R$ with $\pi(A) = h^{-1}(0)$ and $\pi(B) = h^{-1}(1)$. Thus $f := h \circ \pi : X \rightarrow R$ is the required G invariant definable map. \square

Proof of Theorem 1.2. To prove Theorem 1.2, we prove that there exists a definable G retraction $F : X \times [0, 1]_R \rightarrow (Y \times [0, 1]_R) \cup (X \times \{0\})$.

By Theorem 2.1, there exist a G invariant definable open neighborhood U of Y in X and a definable strong G deformation retraction $H : \text{cl } U \times [0, 1]_R \rightarrow \text{cl } U$ from $\text{cl } U$ to Y . By Proposition 2.2, we have a G invariant definable map $\lambda : X \rightarrow [0, 1]_R$ with $\lambda^{-1}(0) = X - U$ and $\lambda^{-1}(1) = Y$. Put $B = \{(x, t) \in \text{cl } U \times [0, 1]_R \mid \frac{1}{2} \leq \lambda(x) < 1, 2(1 - \lambda(x)) \leq t \leq 1\}$, $C = \{(x, t) \in \text{cl } U \times [0, 1]_R \mid \frac{1}{2} \leq \lambda(x) < 1, 0 \leq t \leq 2(1 - \lambda(x))\}$, $D = \{(x, t) \in \text{cl } U \times [0, 1]_R \mid 0 \leq \lambda(x) \leq \frac{1}{2}\}$, and $E = (X - U) \times [0, 1]_R$. Then B, C, D, E are G invariant definable subsets of $X \times [0, 1]_R$ such that $X \times [0, 1]_R = (Y \times [0, 1]_R) \cup B \cup C \cup D \cup E$, D and E are closed in $X \times [0, 1]_R$. The map $\psi : C \rightarrow [0, 1]_R$ defined by $\psi(x, t) = \frac{t}{2(1-\lambda(x))}$ is a G invariant definable function. Put $B' = B \cup (Y \times [0, 1]_R)$. We define a definable G retraction $F : X \times [0, 1]_R \rightarrow (Y \times [0, 1]_R) \cup (X \times \{0\})$, $F(x, t) =$

$$\begin{cases} (r(x), t - 2(1 - \lambda(x))), & (x, t) \in B' \\ (H(x, \psi(x, t)), 0), & (x, t) \in C \\ (H(x, 2t\lambda(x)), 0), & (x, t) \in D \\ (x, 0), & (x, t) \in E \end{cases},$$

where $r := H(\cdot, 1)$. Then F is a well-defined G map with the definable graph.

To prove continuity of F , it suffices to check that for a point y of Y , $F(x, t)$ converges to $(y, 0)$ if $(x, t) \in C$ and (x, t) tends to $(y, 0)$. Since H is continuous at (y, t) , for any $\epsilon > 0$, there exists $\delta' > 0$ such that $\|x - y\| < \delta', |t' - t| < \delta' \Rightarrow \|H(x, t') - H(y, t)\| < \epsilon$, where $\|z\|$ denotes the standard norm of z in a G representation containing X .

Fix $y \in Y, \epsilon > 0$. We define a func-

tion $\phi : [0, 1]_R \rightarrow R$, $\phi(t) = \min\{\sup\{\delta' > 0 \mid \|x - y\| < \delta', |t' - t| < \delta' \Rightarrow \|H(x, t') - H(y, t)\| < \epsilon\}, 1\}$. Then ϕ is a positive function with the definable graph. By 3.1.2, 3.1.6 [1], there exist points $0 = a_0 < a_1 < \dots < a_k = 1$ in $[0, 1]_R$ such that for each j with $0 \leq j \leq k - 1$, $\phi|_{(a_j, a_{j+1})_R}$ is constant, or strictly monotone and continuous. Moreover $\lim_{x \rightarrow a_j+0} \phi(x)$ and $\lim_{x \rightarrow a_j-0} \phi(x)$ exist in R . By construction of ϕ , $\lim_{x \rightarrow a_j+0} \phi(x)$, $\lim_{x \rightarrow a_j-0} \phi(x)$ are positive. Thus modifying ϕ , if necessary, we may assume that for each j with $0 \leq j \leq k - 1$, $\phi|_{[a_j, a_{j+1}]_R}$ is a positive definable function. Since $[a_j, a_{j+1}]_R$ is definably compact, $\phi|_{[a_j, a_{j+1}]_R}$ has the minimum $\delta_j > 0$. Let $\delta = \min\{\min_j \delta_j, \min_j \phi(a_j)\} > 0$. Then $\|x - y\| < \delta \Rightarrow \|H(x, t) - H(y, t)\| = \|H(x, t) - H(y, t)\| < \epsilon$ for any $t \in [0, 1]_R$. Thus $F(x, t) \rightarrow (y, 0)$ as $(x, t) \rightarrow (y, 0)$. Note that $\lim_{(x,t) \rightarrow (y,0), (x,t) \in C} \psi(x, t)$ does not necessarily exist. \square

References

- [1] L. van den Dries, *Tame topology and o-minimal structures*, Lecture notes series **248**, London Math. Soc. Cambridge Univ. Press (1998).
- [2] L. van den Dries and C. Miller, *Geometric categories and o-minimal structures*, Duke Math. J. **84** (1996), 497-540.
- [3] T. Kawakami, *Definable C^r groups and proper definable actions*, Bull. Fac. Ed. Wakayama Univ. Natur. Sci. **58** (2008), 9-18.
- [4] T. Kawakami, *Definable G CW complex structures of definable G sets and their applications*, Bull. Fac. Ed. Wakayama Univ. Natur. Sci. **54** (2004), 1-15.
- [5] T. Kawakami, *Equivariant differential topology in an o-minimal expansion of the field of real numbers*, Topology Appl. **123** (2002), 323-349.
- [6] M. Shiota, *Geometry of subanalytic and semialgebraic sets*, Progress in Mathematics **150**, Birkhäuser, Boston, 1997.